CMS'05 Symposium on

Mathematical Methods in Optimal Control

organized by

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Institute of Automatic Control, AGH University of Science and Technology, Cracow

- Lorenzo Freddi, Universita di Udine, Italy
 Variational convergence methods in optimal control theory
- Stanisław Walczak, University of Lodz, Poland
 On the Stability of Critical Points of Functionals and Solutions to Boundary Value Problems
- Nikolai P. Osmolovskii, Systems Research Institute, Warsaw, Poland
 Second Order Optimality Conditions for a Control with Continuous and Bang-Bang Components
- Andrei Dmitruk, Russian Academy of Sciences, Moscow, Russia
 Jacobi type conditions for singular extremals
- Nikolaos S. Papageorgiou, National Technical University of Athens, Greece
 Degree Theory and Multiple Solutions for Nonlinear Elliptic Equations
- Sabine Pickenhain, Valeria Lykina, BTU Cottbus, Germany Infinite horizon optimal control problems theory and applications
- Stanisław Migórski, Jagiellonian University, Cracow, Poland
 Optimal Control of Elastic and Viscoelastic Dynamic Contact Problems with Applications
- J. Frédéric Bonnans, Julien Laurent-Varin, INRIA, France, Felipe Alvarez, Universidad de Chile, Chile
 - Logarithmic penalty for optimal control problems
- Verena Petzet, Kati Sternberg, Kurt Chudej, Hans Josef Pesch, University of Bayreuth, Germany
 - **Applications of PDE Constrained Optimization**
- Christof Büskens, Universität Bremen, Germany
 Suboptimal Improvement of the Classical Riccati Controller
- Ursula Felgenhauer,BTU Cottbus, Germany
 Primal and dual sensitivity approaches for bang-bang optimal controls
- Andrzej Świerniak, Silesian University of Technology, Gliwice, Poland
 Finite and Infinite Dimensional Optimal Control Problems Arising in Cancer Chemotherapy
- Radosław Pytlak, Wojskowa Akademia Techniczna, Warsaw, Poland
 Convergence analysis of preconditioned conjugate gradient algorithms for nonconvex problems with box constraints
- Maciej Szymkat, Janusz Miller, AGH University of Science and Technology, Cracow, Poland
 Direct and indirect optimization of state constrained flight trajectories